

CMP MEDIA LLC

Gamasutra.com

XML

Christoph Luerig
2006 4 25

http://www.gamasutra.com/features/20060417/sondergaard_01.shtml

XML 가 XML 가 (exporter) 가 가 가 DOM() SAX(XML XML) XML XML [RFC 3076] 가 HTML ASCII Unicode

XML XML

DTD 가 DTD XML XML

SCHEMA XML SCHEMA

가 XML

XMLSpy[XMLSpy] 가

Schema XML 가

XML 가

XML XSLT [W3CR] XSLT XML

가

가

XML 가 XML 가

XML XML

XML

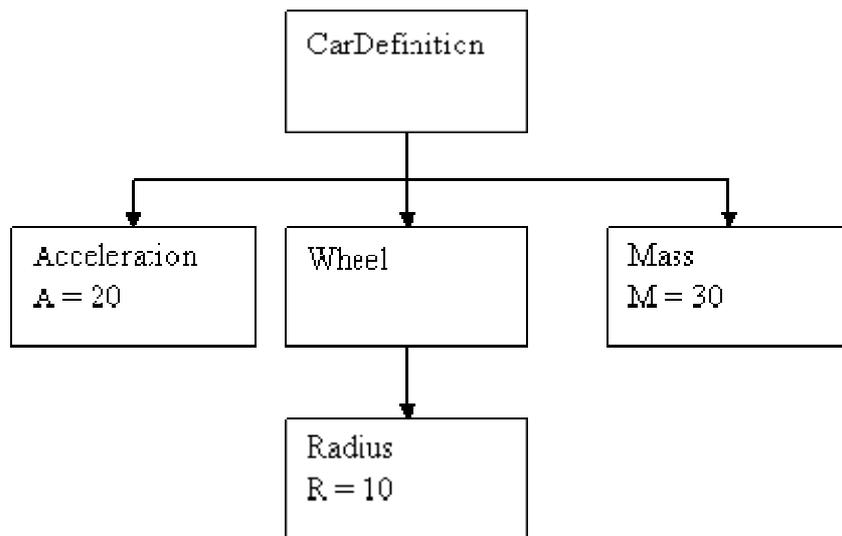
```
<?xml version="1.0" encoding="utf-8"?>
<CarDefinition>
  <!--This is a simple xml test file to check the car definintion
stuff-->
  <Acceleration a="20.0" />
  <Wheel>
    <Radius r="10.0" />
  </Wheel>
  <Mass m="30.0" />
</CarDefinition>
```

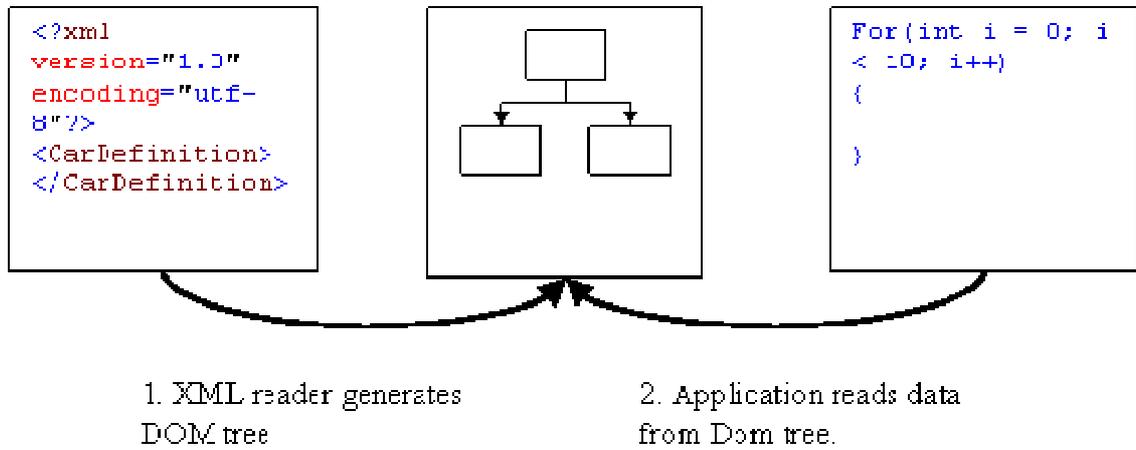
<Radius>10.0</Radius>

XML 가 DOM() DOM
XML 가 SAX(XML API) XML

DOM

가 XML 가 DOM





DOM

TinyXML [SFTXML]

```
TiXmlDocument doc("CarDefinition.xml");
doc.LoadFile();

TiXmlHandle hDoc(&doc);
TiXmlHandle carHeader = hDoc.FirstChildElement("CarDefinition");

Car testCar;
testCar.Parse(carHeader);
```

"LoadFile" 가 가 가
XML 가 가

```
class Car
{
```

```
public:
    void Parse(TiXmlHandle handle);
```

```
protected:
    Wheel m_wheel;
    float m_acceleration;
};
```

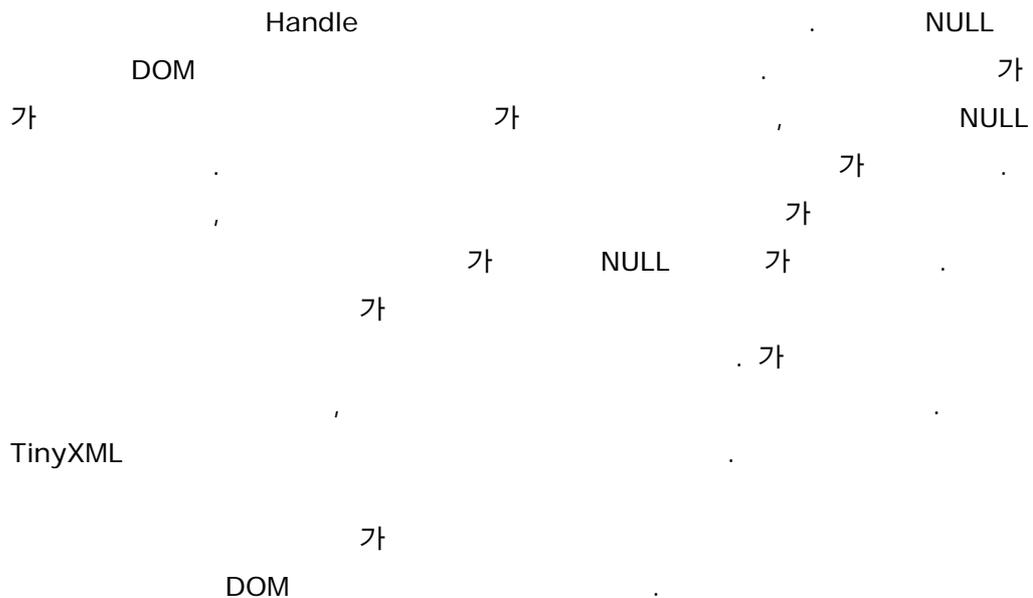
(Parse)

```
void Car::Parse(TiXmlHandle handle)
{
    TiXmlElement* section;

    section = handle.FirstChildElement( "Acceleration" ).Element();
    section->QueryFloatAttribute( "a" , &m_acceleration);

    section = handle.FirstChildElement( "Mass" ).Element();
    section->QueryFloatAttribute( "m" , &m_mass);

    m_wheel.Parse(handle.FirstChildElement( "Wheel" ));
}
```



```

class Wheel
{
public:
    void Parse(TiXmlHandle handle);
protected:
    float m_radius;
};

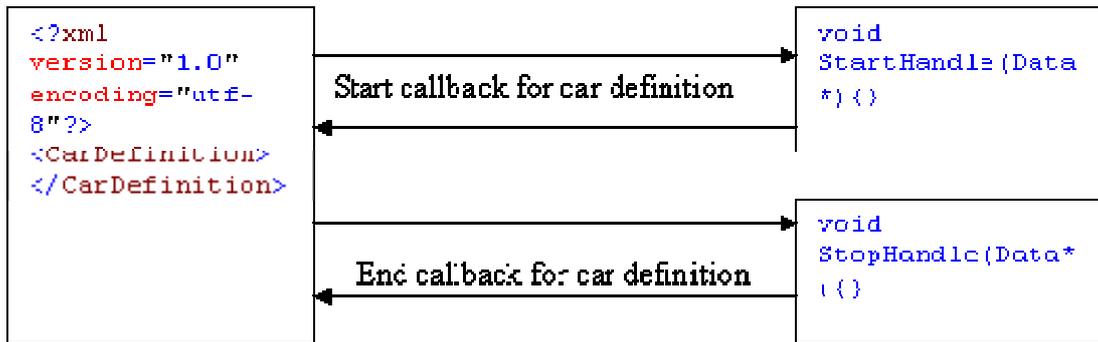
void Wheel::Parse(TiXmlHandle handle)
{
    TiXmlElement* section;
    section = handle.FirstChildElement("Radius").Element();
    section->QueryFloatAttribute("r",&m_radius);
}

```

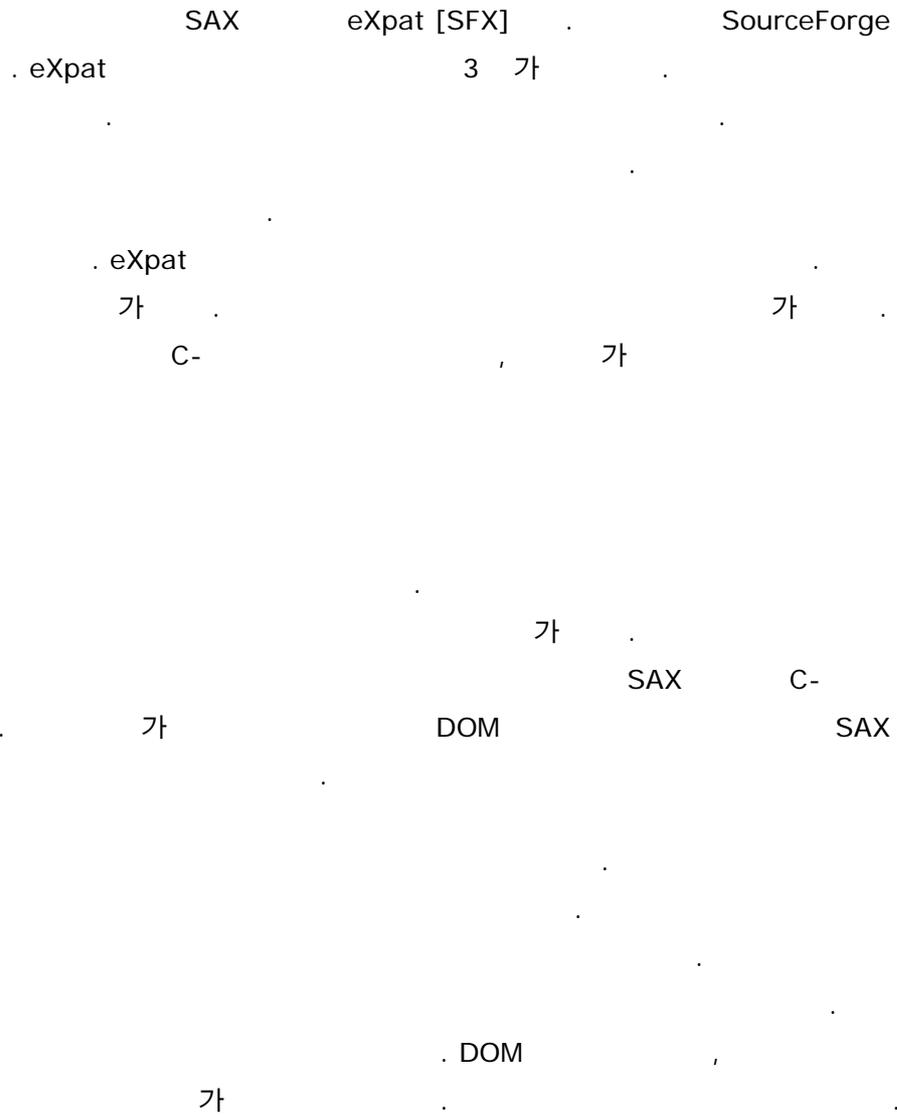
가 , DOM

SAX

SAX "XML API" .
 API .
 가 . SAX DOM
 XML
 DOM SAX SAX
 DOM 가



The parser reads data and feeds it into application.



, 가
, 가

```
class ParseDispatcher
{
public:
    void ParseFile(const char* name, Receiver* startObject);

private:
    stack<Receiver*> m_stackOfReceivers;
    static void XMLCALL start(void *data, const char *el,
        const char **attr);
    static void XMLCALL end(void *data, const char *el);
};
```

eXpat

C

```
class Receiver
{
public:
    virtual Receiver* ProcessData(const char *el, const char **attr)=0;
};
```

ProcessData

가

ProcessData

NULL

ParserDispatcher

```

void XMLCALL ParseDispatcher::start(void *data, const char *el,
const char **attr)
{
    ParseDispatcher* processor = ((ParseDispatcher*)data);
    Receiver* candidate = processor->m_stackOfReceivers.top();
    Receiver* followUp = candidate->ProcessData(el,attr);

    if (followUp)
        processor->m_stackOfReceivers.push(followUp);
    else
        processor->m_stackOfReceivers.push(candidate);
}

void XMLCALL ParseDispatcher::end(void *data, const char *el)
{
    ((ParseDispatcher*)data)->m_stackOfReceivers.pop();
}

void ParseDispatcher::ParseFile(const char* name, Receiver*
startObject)
{
    m_stackOfReceivers.push(startObject);

    char buf[BUFSIZ];
    XML_Parser parser = XML_ParserCreate(NULL);
    XML_SetUserData(parser, this);
    int done;
    FILE* input = fopen(name, "r");
    XML_SetElementHandler(parser, start, end);
    do
    {
        size_t len = fread(buf, 1, sizeof(buf), input);
        done = len < sizeof(buf);
        XML_Parse(parser, buf, len, done);
    }
    while (!done);
    XML_ParserFree(parser);
}

```

```
m_stackOfReceivers.pop();  
}
```

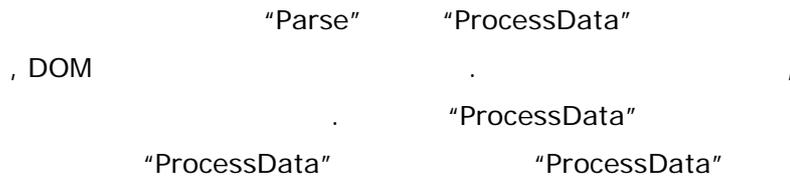
```
, "XML_SetUserData"
```

가 .

가 .

```
class Wheel : public Receiver  
{  
public:  
    virtual Receiver* ProcessData(const char *el, const char **attr);  
  
protected:  
    float m_radius;  
};
```

```
class Car : public Receiver  
{  
public:  
    virtual Receiver* ProcessData(const char *el, const char **attr);  
  
protected:  
    Wheel m_wheel;  
    float m_acceleration;  
    float m_mass;  
};
```



SAX

```

Receiver* Car::ProcessData(const char *el, const char **attr)
{
  if ((strcmp(el, "Wheel")==0))
    return (&_wheel);

  if ((strcmp(el, "Acceleration")==0)&&(strcmp(attr[0], "a")==0))
    sscanf(attr[1], "%f", &_acceleration);
  if ((strcmp(el, "Mass")==0)&&(strcmp(attr[0], "m")==0))
    sscanf(attr[1], "%f", &_mass);

  return (NULL);
}
  
```

("Acceleration", "Mass"),

NULL

```

Receiver* Wheel::ProcessData(const char *el, const char **attr)
{
  if ((strcmp(el, "Radius")==0)&&(strcmp(attr[0], "r")==0))
    sscanf(attr[1], "%f", &_radius);
  return (NULL);
}
  
```

DOM

SAX

DOM

DOM SAX XML

SAX 가

SAX DOM 가

SAX 가 "ProcessData" 가 XML

DOM DOM 가 SAX DOM

XML SAX 가 DOM

SAX SAX 1

DOM DOM SAX

XML DOM 가

SAX 가

DOM 가 가 DOM 가

SAX

-
-
-

DOM

-
-
- XML

가

가

SAX

DOM

SAX

가

가

가

, SAX

XML

2

DOM

, SAX

, SAX

SAX

, SAX

XML

가

SAX

[RFC 3076] <http://rfc.net/rfc3076.html>

[derVlist2002] Eric van der Vlist: *XML Schema*; 2002 O'Reilly Associates

[XMLSpy] http://www.altova.com/products_ide.html

[W3CR] <http://www.w3.org/TR/xslt>

[SFTXml] <http://sourceforge.net/projects/tinyxml>

[SFX] <http://sourceforge.net/projects/expat>